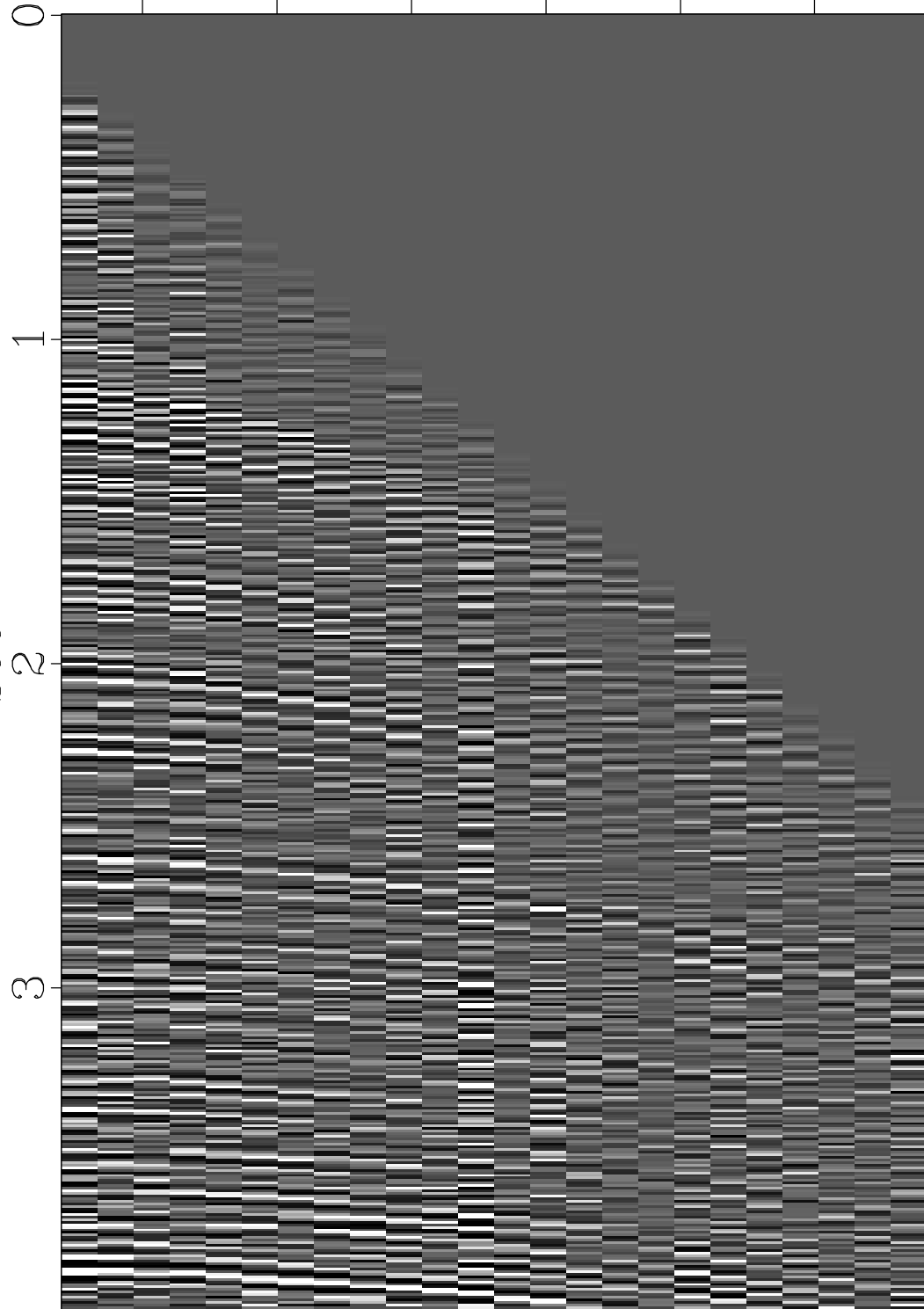


offset(km)

0.5 1 1.5 2 2.5 3



Slowness

0.3 0.4 0.5 0.6 0.7

